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A BAYESIAN TREATMENT OF MULTIVARIATE NORMAL DATA WITH OBSERVATIONS MISSING AT RANDOM

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by

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13

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ABSTRACT

This paper provides a Bayesian formulation of the multivariate normal missing data problem when observations are missing at random. Conjugate prior distributions are considered both when the covariance matrix is known and when it is unknown. When the covariance matrix is known, the posterior distribution of the mean is multivariate normal. When the covariance matrix is unknown, the conditional distribution of the mean given the covariance matrix is again multivariate normal. The kernal of the distribution of the covariance matrix is given and is seen to be difficult to integrate analytically. The paper concludes with some comments on the bivariate case, which is partially tractable for nested missing data.

1. Introduction

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The problem of missing observations in multivariate normal data is important both because of the central role that the normal distribution plays in statistics and because it provides a base from which to test a variety of heuristics for handling missing data. In this paper a Bayesian approach is employed in order to provide a conjugate analysis for the missing data problem.

Attention is restricted to the special case in which the data are missing at random (as discussed by Rubin, 1976), not because this is necessarily the most important case empirically, but because it is a relatively simple, tractable case. It is assumed that the parameters of the process causing the data to be missing are distinct from those of the normal distribution which generates the data.

Let \underline{x} be a p-variate random vector having a normal distribution with mean μ and covariance matrix Σ ; Σ may be known with certainty or unknown. Conjugate prior families for both cases are considered in Section 2. In Section 3, the case when Σ is known is discussed in detail. Remarkably, the conjugate prior and posterior distributions take very simple forms in this case. In Section 4, the more general and difficult case when Σ is unknown is considered. The conditional distribution of μ given Σ is normal, but only the kernel of the marginal distribution of Σ can be given because the resulting integral is difficult to evaluate. Comments on the case when p=2 are given in Section 5.

An important point of comparison for a Bayesian analysis is maximum likelihood estimation, since, asymptotically, posterior distributions are normally distributed with mean given by the maximum likelihood estimate and precision matrix equal to the Fisher information_matrix. (See Walker, 1969, for a simple exposition.) Anderson (1957) gives a treatment of maximum likelihood estimation for both mean and covariance matrix unknown in the special case of nested missing data. In the nested case, the p variables are divided into k blocks, where block i has p variables and $\Sigma p = p$. The missing data form a nested pattern if, whenever data are missing in block j, they are missing in blocks j+1,...,k as well. Thus the variables can be reordered so that the missing data take the following form:

2



"1" indicates presence of data "0" indicates absence of data

Further work on nested data is given by Rubin (1974 and 1976), and a Bayesian analysis based on a full data conjugate prior distribution is given by Chen (1984).

In the non-nested case, iterative methods for finding maximum likelihood estimates have been given by Hartley and Hocking (1971), Orchard and Woodbury (1972), and Beale and Little (1975). See also Dempster, Laird and Rubin (1977). Since the likelihood surface may have multiple maxima (Murray, 1977), there may be difficulties in using numerical methods based on maximizing the posterior density (Stewart and Sorensen, 1981).

2. Conjugate Opinions When Normal Data Are Missing at Random

Let d be a vector of length p comprised of 1's and 0's. Let \mathcal{D} be the set of all such vectors, except for the vector consisting solely of 0's. The \mathcal{D} has $2^{P}-1$ elements. Let d represent the number of 1's in d. It will now be useful to introduce some convenient notation from the APL programming language (Gilman and Rose, 1976).

The symbol / represents the reduction operator. If d and μ are both of length p, and $d \in \mathcal{D}$, then

> $\mu_{\rm d} = d/\mu$ (1)

is the d-reduction of μ . It is a vector whose length is |d| and whose elements are the

•	
	elements of μ corresponding
	then $\mu'_{d} = (1,3)$.
•	
	Note that d can be vie
	presence of a data element a
	means for all p variables, μ_{d}
	A similar operation can
•	
	is the column reduction of Σ
	d columns. Also,
	is the row reduction of Σ , yie
	If Σ is square and symmetric,
	is again square and symmetric,
E.	
	If Σ is the covariance m
	missing data, then
	is the covariance matrix of the
la de la com Sector de la com La como de la com	Let $\underline{x}_{1,\underline{d}},,\underline{x}_{N_{d},\underline{d}}$ be a samp
	normally distributed, and each
	conditional on knowing μ_d and Σ
	$f(\underline{x}_{1,\underline{d}},,\underline{x}_{N_{d},\underline{d}} \mid \underline{\mu}_{\underline{d}}, \boldsymbol{\Sigma}_{\underline{d}})$

It is well known (see Press, 1982, p. 186) that this likelihood function may be rewritten in terms of the sufficient statistics

to the 1's in d. For example, if $\mu' = (1,2,3)$ and d' = (1,0,1),

iewed as a pattern of missing data, where a "1" corresponds to the and a "0" corresponds to its absence. Hence, if μ is the vector of is the mean vector for the observed variables.

be performed on a matrix Σ . The matrix

 Σ , so the resulting matrix will have as many rows as does Σ , and

$$d \neq \Sigma$$

ielding a matrix which has as many columns as Σ and |d| rows. it is easily verified that

$$\underline{d} / \underline{d} + \Sigma = \underline{d} + \underline{d} / \Sigma$$
⁽²⁾

and has |d| rows and columns.

matrix of a set of random variables and d represents a pattern of

$$\Sigma_{\underline{d}} = \underline{d} / \underline{d} + \Sigma \tag{3}$$

observed variables.

sple of N_d vectors of size $|d| \times 1$ that are mutually independent, having missing data pattern d. Then their joint distribution, , is given by

$$E_{d} = \frac{\exp[-\frac{1}{2} \sum_{j=1}^{N_{d}} (\underline{x}_{j,d} - \mu_{d})^{j} \sum_{d}^{-1} (\underline{x}_{j,d} - \mu_{d})]}{(2\pi)^{N_{d}} |\underline{a}|^{j}}$$

(4)

$$\overline{\underline{x}}_{\underline{d}} = \frac{1}{N} \sum_{j=1}^{N} \underline{\underline{x}}_{j,\underline{d}},$$

$$V_{\underline{d}} = \sum_{j=1}^{N} (\underline{x}_{j,\underline{d}} - \overline{\underline{x}}_{\underline{d}}) (\underline{x}_{j,\underline{d}} - \overline{\overline{x}}_{\underline{d}})$$

$$n_{\underline{d}} = N_{\underline{d}} - 1,$$
(5)

so that

$$f(\overline{\underline{x}}_{\underline{d}}, \underline{V}_{\underline{d}} | \underline{\mu}_{\underline{d}}, \underline{\Sigma}_{\underline{d}}) \propto \frac{|\underline{V}_{\underline{d}}|^{(n_{\underline{d}} - |\underline{d}| - 1)/2} \exp \{-\frac{1}{2} \operatorname{tr} \underline{\Sigma}_{\underline{d}}^{-1} [\underline{V}_{\underline{d}} + \underline{N}_{\underline{d}} (\underline{\overline{x}}_{\underline{d}} - \underline{\mu}_{\underline{d}}) (\underline{\overline{x}}_{\underline{d}} - \underline{\mu}_{\underline{d}})']}{|\underline{\Sigma}_{\underline{d}}|^{\frac{N}{2}}}$$
(6)

The conjugate distribution for μ_d given Σ_d is

$$f(\underline{u}_{d} | \Sigma_{d}) = \frac{|\Sigma_{d}|^{-|d|/2}}{2\pi |d|^{1/2}} \exp \left[((-b_{d})/2) (\underline{u}_{d} - \underline{a}_{d})' \Sigma_{d}^{-1} (\underline{\mu}_{d} - \underline{a}_{d})\right]$$
(7)

(Press, 1982, p.83), and the conjugate distribution for μ_d and Σ_d jointly is

$$f(\mu_{d}, \Sigma_{d}) \propto \left| \Sigma_{d}^{-1} \right|^{(\nu_{d}^{+1})/2} \exp \left\{ -\frac{1}{2} \left[(\mu_{d} - \tilde{a}_{d})' \Sigma_{d}^{-1} (\mu_{d} - \tilde{a}_{d}) b_{d} + \operatorname{tr} \Sigma_{d}^{-1} W_{d} \right] \right\}.$$
(8)

In general, let $\theta_d = \mu_d$ when Σ , and consequently Σ_d , is known, and let $\theta_d = (\mu_d, \Sigma_d)$ when Σ is unknown. Thus θ_d is the parameter pertaining to the missing data pattern d. Similarly, let the sufficient statistic $\underline{s}_{\underline{d}} = \overline{\underline{x}}_{\underline{d}}$ when Σ is known, and $\underline{s}_{\underline{d}} = (\overline{\underline{x}}_{\underline{d}}, \nabla_{\underline{d}})$ when Σ is unknown. Finally, let $\underline{t}_{\underline{d}}$ be the hyperparameter: it is $(\underline{a}_{\underline{d}}, \underline{b}_{\underline{d}})$ when Σ is known and $(\underline{a}_d, \underline{b}_d, W_d, \nu_d)$ when Σ is unknown. The property of conjugacy can be written as

$$\frac{f(\underline{s}_{d} | \underline{\theta}_{d}) f(\underline{\theta}_{d} | \underline{t}_{d})}{\int f(\underline{s}_{d} | \underline{\theta}_{d}) f(\underline{\theta}_{d} | \underline{t}_{d}) d\underline{\theta}_{d}} = f(\underline{\theta}_{d} | \underline{t}_{d}, \underline{s}_{d})$$

$$= f(\underline{\theta}_{d} | \underline{q}_{d}'), \qquad (9)$$

where $\underline{t'}_{\underline{d}} = \underline{t'}_{\underline{d}}(\underline{s}_{\underline{d}})$ is the posterior value of the hyperparameter after observing data having sufficient statistic \underline{s}_d .

Now suppose that data are available on various patterns of missing data in \mathcal{D} . The missing data are missing at random, and the parameters governing the process by which data are missed are assumed to be independent of θ . Suppose in particular that $N_d \ge 1$ for each $\underline{d} \in \mathcal{D}_1 \subseteq \mathcal{D}$. Then the likelihood function has the form



$$\Pi_{\underline{d} \in \mathcal{D}_{1}} f(\underline{s}_{\underline{d}} \mid \underline{\theta}_{\underline{d}}).$$
(10)
s that might be considered for this problem is
$$\Pi_{\underline{d} \in \mathcal{D}_{1}} f(\underline{\theta}_{\underline{d}} \mid \underline{t}_{\underline{d}}).$$
(11)

· With this prior distribution, the posterior distribution is proportional to

$$\prod_{\underline{d}\in\mathcal{D}_{\underline{d}}} f(\underline{s}_{\underline{d}} \mid \underline{\theta}_{\underline{d}}) f(\underline{\theta}_{\underline{d}} \mid \underline{t}_{\underline{d}}),$$
(12)

$$\prod_{q \in \mathcal{D}} f(\underline{\theta}_q | \underline{t}'_q)$$
(13)

which is in the same family as the prior distribution. Hence the family in (11) is conjugate to the likelihood given by (10). This analysis holds for missing data from any family having

The next two sections explore the consequences of this theory for the two special cases of interest in this paper: multivariate normal data with known covariance matrix but unknown mean vector, and multivariate normal data with mean vector and covariance matrix both unknown.

3. Normal Data Missing at Random With Unknown Mean and Known Covariance

It is first helpful to introduce additional APL notation. The symbol \setminus is the expansion

is the d-expansion of x; it is a vector of length p (the length of d) having elements of x where the corresponding element of d is 1, and having zeros elsewhere. Thus if d' = (1,0,1,0,1) and $\underline{x}' = (1,2,3)$, then $(\underline{d} \setminus \underline{x})' = (1,0,2,0,3)$. In an analogous way,

$$d + \Sigma$$

The conjugate family given in (11), with factors as in (7), becomes

$$(\mu) = \prod_{d \in \mathcal{D}_1} \frac{\left| \sum_{d} \right|^{-|d|/2}}{(2\pi)^{|d|/2}} \exp \left[\frac{-b_d}{2} (\mu_d - \underline{a}_d)' \sum_{d}^{-1} (\mu_d' - \underline{a}_d) \right].$$

Since μ_{d} appears only in the exponential function, (14) may be rewritten as

$$(\underline{\mu}) \propto \exp\left\{\sum_{\underline{d} \in \mathcal{D}_{1}} \left[\frac{-b_{\underline{d}}}{2} (\underline{\mu}_{\underline{d}} - \underline{a}_{\underline{d}})' \sum_{\underline{d}}^{-1} (\underline{\mu}_{\underline{d}} - \underline{a}_{\underline{d}}) \right] \right\}.$$
(15)

(14)

The sum in (15) is awkward because the quadratic forms which are being added are of different dimensions. They can be made to have the same dimension with the help of the expansion operator.

Let
$$\underline{a}_{d}^{*} = \underline{d} \setminus \underline{a}_{d}$$
, and let $H_{d} = \underline{d} \setminus \underline{d} + b_{d} \Sigma_{d}^{-1}$. Then
 $(\mu_{d} - \underline{a}_{d})' \Sigma_{d}^{-1} (\mu_{d} - \underline{a}_{d}) = (\mu - \underline{a}_{d}^{*})' H_{d} (\mu - \underline{a}_{d}^{*}),$
(16)

since zeros have been introduced in H_d corresponding to the pattern of missing data in d. Anything can appear in the vector that multiplies with H_d in these positions without altering the value of the quadratic form.

Substituting (16) into (15) gives

$$\mathcal{L}(\mu) \propto \exp \left\{ \sum_{\underline{d} \in \mathcal{D}_{1}} \left[-\frac{1}{2} \left(\frac{\mu}{\mu} - \underline{a}_{\underline{d}}^{*} \right)^{\prime} H_{\underline{d}} \left(\frac{\mu}{\mu} - \underline{a}_{\underline{d}}^{*} \right) \right] \right\}.$$
(17)

This kernel has the form of the product of a number of normal distribution kernels for μ , with means a and precision matrices H. The product is also a normal kernel, with precision matrix H = $\sum_{d \in \mathcal{D}_1} H_d$ and mean $\underline{a} = H^{-1} \sum_{d \in \mathcal{D}_1} H_d \underline{a}_d^*$, as long as H is invertible. (H will be invertible if each variable is observed at least once, and this can be assumed without loss of generality.)

Thus, remarkably, the prior family (11) is no more complicated than the full data conjugate prior as long as Σ is known. The nonmissing data combine in the likelihood function and prior distribution to yield a posterior distribution that is a p-dimensional normal distribution.

4. Normal Data Missing at Random With Unknown Mean and Covariance Matrix

In this section the conjugate prior family in (11), with factors given in (8), is studied. In this case,

$$f(\mu, \Sigma) \propto \prod_{d \in \mathcal{D}_1} |\Sigma_d^{-1}|^{(\nu_{d} + 1)/2} \exp \left\{ -\frac{1}{2} \left[(\mu_d - \underline{a}_d)^{\prime} \Sigma_d^{-1} (\mu_d - \underline{a}_d) \mathbf{b}_d + \operatorname{tr} \Sigma_d^{-1} \mathbf{W}_d \right] \right\}.$$
(18)

Since this distribution is the product of normal kernels for μ given Σ , and inverse Wishart

 Σ , and a density on Σ . H. Hence, $f(\Sigma) \propto \frac{1}{|H|}$



needs to be simplified.

Consider the block-partitioned matrix H which has the form

with the H_d down the main diagonal and matrices of zeros off the diagonal. Let $\tilde{I} = (I, I, ..., I)$ be a matrix containing as many $p \times p$ identity matrices as there are matrices down the diagonal of \tilde{H} . Then $H = \tilde{I} \tilde{H} \tilde{I}'$. Also, $\sum_{d \in D_1} H_d \tilde{a}_d^* = \tilde{I} \tilde{H} \tilde{a}^*$, where $a^{*\prime} = (a_1, a_2, ...)$. Then (21) can be rewritten as

 $(\sum_{\underline{d} \in \mathcal{D}_1} H_{\underline{d}})$

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kernels for Σ_d , it is natural-to think of this joint density as the product of a density on μ given

Using the results of Section 3, $f(\mu | \Sigma)$ is again normal with mean a and precision matrix

$$= \prod_{\underline{d} \in \mathcal{D}_{1}} |\Sigma_{\underline{d}}^{-1}|^{\nu_{\underline{d}}^{+1}/2} \exp\left\{-\frac{1}{2}\left(\operatorname{tr} \Sigma_{\underline{d}}^{-1} W_{\underline{d}}^{+} + \underline{a}_{\underline{d}}^{*\prime} H_{\underline{d}}^{\underline{a}} - \underline{a}_{\underline{d}}^{*\prime}\right)\right\}$$

$$= \exp\left\{\frac{1}{2}\left(\sum_{\underline{d} \in \mathcal{D}_{1}} H_{\underline{d}}^{\underline{a}} + \frac{1}{2}\right)^{\prime} H^{-1}\left(\sum_{\underline{d} \in \mathcal{D}_{1}} H_{\underline{d}}^{\underline{a}} - \underline{a}_{\underline{d}}^{*\prime}\right)\right\}.$$

$$(19)$$

To simplify the exponential term, first note that

$$\underline{a}_{\underline{d}}^{*\prime} H_{\underline{d}} \underline{a}_{\underline{d}}^{*} = \underline{a}_{\underline{d}}^{\prime} \sum_{\underline{d}}^{-1} \underline{b}_{\underline{d}} \underline{a}_{\underline{d}}$$
$$= \operatorname{tr} \underline{b}_{\underline{d}} \sum_{\underline{d}}^{-1} \underline{a}_{\underline{d}} \underline{a}_{\underline{d}}^{\prime} .$$

$$\Sigma_{\underline{d}}^{-1} W_{\underline{d}} + \underline{a}_{\underline{d}}^{*\prime} H_{\underline{d}} \underline{a}_{\underline{d}}^{*} = \text{tr } \Sigma_{\underline{d}}^{-1} (W_{\underline{d}} + \underline{b}_{\underline{d}} \underline{a}_{\underline{d}} \underline{a}_{\underline{d}}^{\prime}).$$
(20)

$$H_{\underline{d}} \; \underline{a}_{\underline{d}}^*)' \; H^{-1} \; (\sum_{\underline{d} \in \mathcal{D}_1} H_{\underline{d}} \; \underline{a}_{\underline{d}}^*), \text{ where } H = \sum_{\underline{d} \in \mathcal{D}_1} H_{\underline{d}}$$
(21)

$$\tilde{H} = \begin{pmatrix} H_1 & 0 & \cdot & \cdot & 0 \\ 0^1 & H_2 & & & \\ \cdot & & \cdot & & \\ 0 & & \cdot & \cdot & \\ 0 & & & \cdot & \cdot \end{pmatrix},$$

$$\mathbf{a}_{d}^{*)'} \mathbf{H}^{-1} \left(\sum_{\underline{q} \in \mathcal{D}_{1}} \mathbf{H}_{\underline{q}} \mathbf{a}_{\underline{q}}^{*} \right) = \mathbf{a}^{*'} \mathbf{\tilde{H}} \mathbf{\tilde{I}}' (\mathbf{\tilde{I}} \mathbf{\tilde{H}} \mathbf{\tilde{I}}')^{-1} \mathbf{\tilde{I}} \mathbf{\tilde{H}} \mathbf{a}^{*}.$$
(22)

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Now rewrite (20) so that it may be combined with (22):

$$\sum_{e} \mathcal{D}_{i} \operatorname{tr} \sum_{d}^{-1} (W_{d} + b_{d} \underline{a}_{d} \underline{a}_{d}') = \operatorname{tr} \sum_{d} \mathcal{D}_{i} \sum_{d}^{-1} (W_{d} + b_{d} \underline{a}_{d} \underline{a}_{d}')$$

= tr $\widetilde{I} \widetilde{W} \widetilde{H} \widetilde{I},$

where \tilde{W} is a block-diagonal matrix with \underline{d}^{th} block given by

$$\setminus \underline{d} \rightarrow tr (W_d + b_d \underline{a}_d \underline{a}_d').$$

Hence the argument of the exponential function in (19) can be written as

$$a^{*'} \tilde{H} \tilde{I}' (\tilde{I} \tilde{H} \tilde{I}')^{-1} \tilde{I} \tilde{H} a^{*} - tr \tilde{I} \tilde{W} \tilde{H} \tilde{I}'$$

$$= tr a^{*'} \tilde{H} \tilde{I}' (\tilde{I} \tilde{H} \tilde{I})^{-1} \tilde{I} \tilde{H} a^{*} - tr \tilde{I} \tilde{W} \tilde{H} \tilde{I}'$$

$$= tr \left[(\tilde{I} \tilde{H} \tilde{I}')^{-1} \tilde{I} \tilde{H} a^{*} a^{*'} \tilde{H} \tilde{I}' \right] - tr \left[(\tilde{I} \tilde{H} \tilde{I}')^{-1} (\tilde{I} \tilde{H} \tilde{I}') \tilde{I} \tilde{W} \tilde{H} \tilde{I}' \right]$$

$$\overset{\circ}{=} tr \left[(\tilde{I} \tilde{H} \tilde{I}')^{-1} \tilde{I} \tilde{H} a^{*} a^{*'} - \tilde{I}' \tilde{I} \tilde{W} \tilde{H} \tilde{I}' \right]. \qquad (25)$$

(23)

(24)

Let $\tilde{W}^* = a^* a^{*\prime} - \tilde{I}^{\prime} \tilde{I} \tilde{W}$ Then

 $\langle \cdot \rangle$

$$f(\Sigma) \propto \frac{1}{|H|^{\frac{1}{2}}} \sum_{\underline{d} \in \mathcal{D}_1} |\Sigma_{\underline{d}}^{-1}|^{(\nu_{\underline{d}}^{+1})/2} \exp\left\{-\frac{1}{2} \operatorname{tr} \left[(\tilde{I} \ \tilde{H} \ \tilde{I}')^{-1} \ \tilde{I} \ \tilde{H} \ \tilde{W} \ \tilde{H} \ \tilde{I}' \right] \right\}.$$
(26)

The distribution whose kernel appears in (26) may be regarded as a generalization of the inverse Wishart distribution. This kernel apparently cannot be integrated in closed form. And unlike the case of Section 3, the kernel does not reduce to the full-data conjugate case, which would be an inverted Wishart distribution.

5. Data Missing at Random When p = 2

Surprisingly, the bivariate normal case of data missing at random does not, in general, lead to a mathematically tractable form for (26). An examination of the bivariate kernel reveals the complexity inherent in the missing data problem.

Since it is the inverses of the covariance matrices Σ_d which appear in (26), it is helpful to reparametrize in terms of $\Sigma_{\underline{d}}^{-1}$. Let $\Sigma_{(1,0)}^{-1} = Z_1^*$, $\Sigma_{(0,1)}^{-1} = Z_2^*$, and

 $\Sigma_{(1)}^{-1}$ Then it is easy to see that and (27) $Z_2^* = \frac{1}{(\sigma_1^2 \sigma_2^2 - \sigma_{12}^2) Z_1} = \frac{(Z_1 Z_2 - Z_{12}^2)}{Z_1}.$ In other words, the precisions are defined differently in terms of σ_1^2, σ_2^2 , and σ_{12} in different dimensions. Also, let (a_1, b_1, w_1, v_1) be the hyperparameters corresponding to $\underline{d}' = (1,0)$ and a_2, b_2, w_2, v_2 be the hyperparameters corresponding to $\underline{d}' = (0,1)$. For the totally observed data, represented by $\underline{d}' = (1,1)$, let the hyperparameters be $(\underline{a}_3, \underline{b}_{12}, \underline{w}_3, \underline{v}_{12})$, where and Then, since the Jacobian of the transformation from Σ to Σ^{-1} is $|\Sigma^{-1}|^{-(p+1)} = |Z|^{-3}$, (26) may be rewritten as $f(Z) \propto$ $f(Z) \propto \frac{\left| b_{1}Z_{1}^{*} + b_{1}Z_{1} \right|^{2}}{\left| b_{1}Z_{12}^{*} + b_{1}Z_{12} \right|^{2}} \cdot (Z_{1}Z_{2} - Z_{12}^{2})^{1} \right|^{(\nu_{12}^{+1})/2}}$

+ $2(w_{12} + b_{12}a_{31}a_{32})Z_{1}$

$$\sum_{i=1}^{-1} \sum_{j=1}^{-1} \left(\begin{array}{cc} \sigma_{1}^{2} & \sigma_{12} \\ \sigma_{12} & \sigma_{2}^{2} \end{array} \right)^{-1} \\ = Z_{1} & Z_{12} \\ Z_{12} & Z_{2} \\ Z_{12} & Z_{2} \\ \end{array} = Z .$$

$$Z_{12}^{*} = \frac{1}{(\sigma_{1}^{2} \sigma_{2}^{2} - \sigma_{12}^{2}) Z_{2}} = \frac{(Z_{1} Z_{2} - Z_{12}^{2})}{Z_{2}} \\ Z_{1}^{*} = \frac{1}{(\sigma_{1}^{2} \sigma_{2}^{2} - \sigma_{12}^{2}) Z_{2}} = \frac{(Z_{1} Z_{2} - Z_{12}^{2})}{Z_{2}} \\ Z_{1}^{*} = \frac{1}{(\sigma_{1}^{2} \sigma_{2}^{2} - \sigma_{12}^{2}) Z_{2}} = \frac{(Z_{1} Z_{2} - Z_{12}^{2})}{Z_{2}} \\ Z_{1}^{*} = \frac{1}{(\sigma_{1}^{2} \sigma_{2}^{2} - \sigma_{12}^{2}) Z_{2}} = \frac{(Z_{1} Z_{2} - Z_{12}^{2})}{Z_{2}} \\ Z_{1}^{*} = \frac{1}{(\sigma_{1}^{2} \sigma_{2}^{2} - \sigma_{12}^{2}) Z_{2}} = \frac{(Z_{1} Z_{2} - Z_{12}^{2})}{Z_{2}} \\ Z_{1}^{*} = \frac{1}{(\sigma_{1}^{2} \sigma_{2}^{2} - \sigma_{12}^{2}) Z_{2}} = \frac{(Z_{1} Z_{2} - Z_{12}^{2})}{Z_{2}} \\ Z_{1}^{*} = \frac{1}{(\sigma_{1}^{2} \sigma_{2}^{2} - \sigma_{12}^{2}) Z_{2}} = \frac{(Z_{1} Z_{2} - Z_{12}^{2})}{Z_{2}} \\ Z_{1}^{*} = \frac{1}{(\sigma_{1}^{2} \sigma_{2}^{2} - \sigma_{12}^{2}) Z_{2}} = \frac{(Z_{1} Z_{2} - Z_{12}^{2})}{Z_{2}} \\ Z_{2}^{*} = \frac{1}{(\sigma_{1}^{2} \sigma_{2}^{2} - \sigma_{12}^{2}) Z_{2}} = \frac{(Z_{1} Z_{2} - Z_{12}^{2})}{Z_{2}} \\ Z_{2}^{*} = \frac{(Z_{1}^{*} Z_{2} - Z_{12}^{*})}{Z_{2}} \\ Z_{$$

10

$$\frac{a_{3}}{a_{3}} = (p_{31}, a_{32}) \\
W_{3} = \begin{pmatrix} W_{31}, W_{12} \\ W_{31}, W_{12} \\ W_{12}, W_{32} \end{pmatrix}$$

$$\frac{1}{Z_{1}} \frac{1}{b_{12}Z_{12}} | \overset{v}{=} Z_{1}^{*(\nu_{1}+1)/2} Z_{2}^{*(\nu_{2}+1)/2}$$

$$\frac{b_{2}Z_{2}^{*} + b_{12}Z_{2}}{b_{2}Z_{2}^{*} + b_{12}Z_{2}} | \frac{1}{2^{1}} \sum_{j=1}^{2^{1}} e^{-j\omega_{j}} \left\{ (w_{31} + b_{12})^{2} + (w_{32} + b_{12})^{2} - (w_{31} + b_{12})^{2} - (w_{32} + b_{12})^{2} - (w_{$$

$$+ (w_{2}+b_{2}a_{2}^{2})Z_{2}^{*} - \frac{Z_{1}Z_{2}}{(Z_{1}Z_{2}-Z_{12}^{2})[\{b_{1}b_{2}+(b_{1}+b_{2}+b_{12})b_{12}\}Z_{1}Z_{2}-b_{1}b_{2}Z_{12}^{2}]}{(Z_{1}Z_{2}-z_{12}^{2})[\{b_{1}b_{2}+(b_{1}+b_{2}+b_{12})b_{12}\}Z_{1}Z_{2}-b_{1}b_{2}Z_{12}^{2}]}$$

$$+ \left[b_{1}^{2}b_{1}a_{3}a_{1}Z_{2}^{*}Z_{2}+b_{2}^{2}b_{1}a_{2}a_{3}Z_{1}Z_{2}^{*}+b_{1}^{2}b_{2}a_{1}^{2}Z_{1}^{*}Z_{2}^{*}$$

$$+ b_{1}b_{2}^{2}a_{2}^{2}Z_{1}^{*}Z_{2}^{*} +b_{1}b_{2}b_{12}Z_{1}^{*}Z_{2}^{*}f_{1}(Z_{1},Z_{2},Z_{12})$$

$$+ b_{1}b_{12}^{2}Z_{1}^{*}f_{2}(Z_{1},Z_{2},Z_{12}) + b_{2}b_{12}^{2}Z_{1}^{*}(Z_{1},Z_{2},Z_{12})$$

$$+ b_{1}^{3}(Z_{1}Z_{2}-Z_{12}^{3})\left[a_{2}^{2}Z_{1}+2a_{3}a_{3}Z_{12}+a_{32}^{2}Z_{2}^{*}\right]\right]\}], \qquad =$$

(28)

0 11

where

$$f_{1}(Z_{1}, Z_{2}, Z_{12}) = 2a_{1}a_{31}Z_{1} + 2a_{2}a_{32}Z_{2} + 2a_{1}a_{32}Z_{12}$$

$$+ 2a_{2}a_{31}Z_{12} - a_{1}a_{2}Z_{12}$$

$$f_{2}(Z_{1}, Z_{2}, Z_{12}) = a_{1}a_{31}(Z_{1}Z_{2}-Z_{12}^{2}) + (a_{31}^{2}-a_{1}a_{31})Z_{12}^{2}$$

$$+ 2a_{31}a_{32}Z_{2}Z_{12} + a_{1}a_{31}Z_{1}Z_{12} + a_{32}^{2}Z_{2}^{2}$$

$$f_{3}(Z_{1}, Z_{2}, Z_{12}) = a_{2}a_{32}(Z_{1}Z_{2}-Z_{12}^{2}) + (a_{2}^{2}-a_{2}a_{32})Z_{12}^{2}$$

$$+ 2a_{31}a_{32}Z_{1}Z_{12} + a_{2}a_{32}Z_{2}Z_{12} + a_{31}^{2}+Z_{12}^{2}$$

Unfortunately, substitution for Z_1^* and Z_2^* does not allow (28) to be written in a simple form, and there is no apparent way to integrate (28) with respect to Z_1 , Z_2 and Z_{12} over the region given by $Z_1 > 0$, $Z_2 > 0$, and $(Z_1 Z_2 - Z_{12}^2) > 0$ except by using numerical methods.

If the missing data are assumed to form a nested pattern, the results of Chen (1984) may be used to find the integrating constant for the kernel in (18). Assume that data are missing on X_2 but not on X_1 . The kernel can be reparametrized from $(\mu_1, \sigma_2, \sigma_1^2, \sigma_2^2, \sigma_{12})$ to the distinct parameters $(\mu_1, \sigma_1^2, \alpha, \beta, \sigma_{22:1}^2)$, where

 $\alpha = \mu_2 - \beta \mu_1,$

 $\sigma_{2^{5+1}}^2 = \sigma_2^2 - \sigma_{12}^2 / \sigma_1^2 .$

 $\beta = \sigma_{12}^{\prime}/\sigma_{1}^{2},$

and

Chen demonstrates that these distinct parameters are independent when the missing data form a nested pattern. (Chen actually assumes a complete data conjugate prior instead of the more general conjugate prior described herein. However, in the case of nested missing data, his posterior kernel has the same form as the general prior kernel given in (18).)

In our notation, Chen's results imply that

(a)
$$\sigma_1^{-2} \sim \text{Wishart} \left(\frac{(b_1 + b_{12})(w_1 + w_{31}) + b_1 b_{12}(a_1 + b_{31})^2}{b_1 + b_{12}}, v_1 + v_{12} + 1 \right)$$

(b)
$$\mu_1 \left(\sigma_1^2 \sim \text{Normal} \left(\frac{b_1 a_1 + b_1 a_3}{b_1 + b_{12} 31}, (b_1 + b_{12})^{-1} \sigma_1^2 \right) \right)$$

(c)
$$(\alpha, \beta) | \sigma_{22^{1}1}^{2} \sim \text{matrix Normal} \left(\begin{pmatrix} a_{32} - \frac{w_{12}}{w_{31}} & a_{31}, \frac{w_{12}}{w_{31}} \end{pmatrix}, \\ \sigma_{22^{1}1}^{2} \begin{pmatrix} b_{12}^{-1} + a_{31}^{2}/w_{31} & -a_{31}^{2}/w_{31} \\ -a_{31}^{2}/w_{31} & 1/w_{31} \end{pmatrix} \right)$$

(d) $\sigma_{22\cdot1}^2 \sim \text{Wishart } (w_{32} - w_{12}^2/w_{31}, v_{12}+1).$

form is quite cumbersome.

interesting generalization of the Wishart density:

$$f(z_{1}, z_{2}, z_{12}) = A^{2(\nu_{1} + \nu_{12} + 1)} [w_{32} - w_{12}^{2}/w_{31}]^{2(\nu_{12} + 1)}$$

$$\cdot 2^{-\lambda(\nu_{1} + 2\nu_{12} + 2)} \sqrt{\frac{(b_{1} + b_{12})}{\sqrt{2\pi}}} \sqrt{w_{31}} \frac{1}{\Gamma((\nu_{1} + \nu_{12} + 1)/2) \Gamma((\nu_{12} + 1)/2)}$$

where

 A = $\left[\frac{(b_1+b_1)(w_1+w_2)}{1} \right]$

Therefore the integrating constant for the kernel in (18) is known in the special case of nested missing data. By pulling out the conditional normal density on (μ_1, μ_2) given $(\sigma_1^2, \sigma_2^2, \sigma_{12})$, the complete marginal density for $(\sigma_1^2, \sigma_2^2, \sigma_{12})$ can also be obtained, but as indicated by (19), its

The density for (z_1, z_2, z_{12}) has a simpler form in this special case and appears to be an

 $\cdot z_{2}^{-(\nu_{1}+1)/2} (z_{1}z_{2}-z_{12}^{2})^{(\nu_{1}+\nu_{12}-4)/2} \exp \left\{ \frac{1}{2} \left[\beta_{1}z_{1}+\beta_{12}z_{12}+\beta_{2}z_{2}+\beta_{3}\frac{z_{12}^{-2}}{z_{2}}+\beta_{4}\frac{1}{z_{2}} \right] \right\}$

$$\frac{a_{1}^{31}+b_{1}b_{12}^{2}(a_{1}+a_{31})^{2}}{a_{1}+b_{12}^{2}}]^{\frac{1}{2}(\nu_{1}+\nu_{12}+1)}$$

$$\beta_{1} = \frac{(a_{1} - a_{31})^{2} b_{1} b_{1} - a_{1}^{2} b_{1}^{2} - 2w_{1}(b_{1} + b_{12})}{b_{1} + b_{12}}$$

$$\beta_{12} = 2a_{31}a_{32}(b_{12} - 1) - 2w_{12}$$

$$\beta_{2} = a_{32}^{2}(b_{12} - 1) - w_{32}$$

$$\beta_{3} = \frac{(a_{31} - a_{1})^{2} b_{1} b_{1} + a_{1}^{2} b_{1}^{2} + w_{1}(b_{1} + b_{12})}{b_{1} + b_{12}}$$

and

$$\beta_4 = \frac{a_1^2 b_1^2}{b_1^2 + b_{12}} \ .$$

Chen's results apply to <u>any</u> nested configuration of missing data, so the complete density for (18) may always be found in the nested missing data case. Chen's method does not generalize to the non-nested case, however, since distinct parameters can no longer be identified. A direct method of integration is still required in the general case.

13

6. Conclusion

We have shown that the conjugate-prior analysis of multivariate normal data missing at random is tractable when the covariance matrix can³ be assumed to be known, and difficult otherwise. The kernel for a useful generalization of the inverse Wishart distribution is given, but we do not know how to integrate it in non-nested cases. Perhaps stimulated by this notice of an unsolved problem, others will take up the challenge. Anderson, T. W. (1957) "Maximum likelihood estimates for a multivariate normal distribution when some observations are missing." Journal of the American Statistical Association, 52, 200-203.

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20. ABSTRACT (continued)

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6

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covariance matrix is given and is seen to be difficult to integrate analytically. The paper concludes with some comments on the bivariate case, which is partially tractable for nested missing data.

Gen.

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